Notice of References Cited

Application/Control No. 10/538,770	Applicant(s)/Patent Under Reexamination OKAZAKI ET AL.		
Examiner	Art Unit		
MCDIEUNEL MARC	3664	Page 1 of 1	

U.S. PATENT DOCUMENTS

	Old Filter December 1				
*		Document Number Country Code-Number-Kind Code	Date MM-YYYY	Name	Classification
*	Α	US-5,956,465	09-1999	Takagi et al.	700/255
*	В	US-7,053,579	05-2006	Moridaira, Tomohisa	318/568.12
*	С	US-6,917,176	07-2005	Schempf et al.	318/568.11
*	D	US-3,851,769	12-1974	Noguchi et al.	414/744.3
*	Е	US-4,166,543	09-1979	Dahlstrom, Lars	700/251
*	F	US-4,791,588	12-1988	Onda et al.	700/260
	G	US-		-	
	Н	US-			
	1	US-			
	J	US-			
	К	US-			
	L	US-			
	м	US-			

FOREIGN PATENT DOCUMENTS

*		Document Number Country Code-Number-Kind Code	Date MM-YYYY	Country	Name	Classification
	N					
	0					
	Р					
	Q					
	R					
	s					
	Т					

NON-PATENT DOCUMENTS

*		Include as applicable: Author, Title Date, Publisher, Edition or Volume, Pertinent Pages)			
	U	Tan et al., Hybrid system design for singularityless task level robot controllers, 2000, IEEE, pg. 3007-3012			
	v	Gerke et al., Fuzzy collision avoidance for industrial robots, 1995, IEEE, pg. 510-517			
	w	Akella et al., Discontinuous model-based adaptive control for robots executing free and constrained tasks, 1994, IEEE, pg. 3000-3007			
	x	Hirana et al., Realization of skill controllers for manipulation of deformable objects based on hybrid automata, 2001, IEEE, pg. 2674-2679			

"A copy of this reference is not being furnished with this Office action. (See MPEP § 707.05(a).)
Dates in MM-YYYY format are publication dates. Classifications may be US or foreign.